

# **Temposonics**®

Absolute, Non-Contact Position Sensors

## M-Series PWM

**Temposonics MH** Measuring Length 50 - 2500 mm



### **Compact Sensor for Mobile Hydraulics**

- Linear, absolute Measurement in Hydraulic Cylinders
- Non-Contact Sensing with Highest Durability
- Compact Dimensions
- Accuracy: Linearity Tolerance < ± 0,04%
- Hysteresis < ± 0,1 mm
- Direct PWM Output: Displacement
- Power Supply: 12/24 VDC
- Immunity against electromagnetic HF-fields up to 200 V/m
- Shockrating: 100 g (singlehit) / IEC 68-2-27



#### **Designed for the Mobile World**

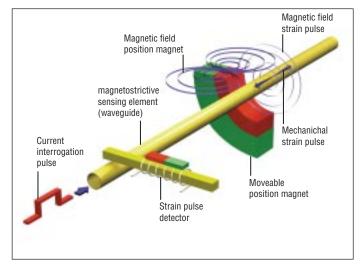
M-Series sensors were designed with the "mobile" world in mind, and have been validated in the field by customers worldwide. Performance is second tonone; high accuracy, 200 V/m EMI position output. Ruggedness is "designed in", 100 g shock rating. The MH sensor can be fully sealed and embedded in a cylinder to ensure a long operation life. The direct connection to the Temposonics<sup>®</sup> M12 connector system and other proven mobile connectors are possible.



#### Magnetostriction

The absolute **Temposonics**<sup>®</sup> linear position sensors are based on the MTS developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical height precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting. Sensor integrated signal processing transforms the measurements directly into market standard outputs. The non-contact principle - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.

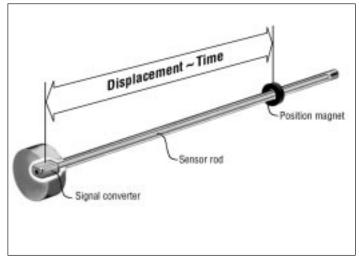
#### **Measuring Principle**



#### Temposonics MH - High Pressure Compact Sensor Measuring Range 50 2500 mm

Temposonics MH, the new compact stainless steel position sensor is designed for installation into hydraulic cylinders, specifically for use in clevis head mobile cylinders or any space limited cylinder applications. MH type sensors are ideal choices for a wide range of standard hydraulic cylinders. Magnetostrictive displacement sensors, high quality cylinders and precise control valves form ideal driving systems for technically demanding of mobile hydraulics.

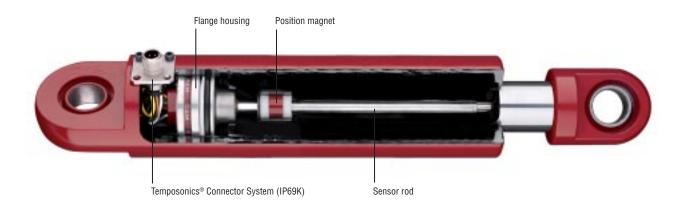
#### Measuring Prinicple (simplified illustration)



#### **Simple Mechanics**

The extremely rugged sensor consist of the following main parts:

- . The flange housing with singal converter and built-in electronics
- The pressure-proof sensor pipe (up to 450 bar) with flange protects the internal sensing element, the waveguide system. It fits into the bored piston rod
- The position magnet, only moving part is mounted into the piston bottom. This permanent magnet travels wearfree and contactless along the stationary sensor tube. Its magnetic field starts the measurement signal through the sensors rod wall
- The innovative Connector System can easily be mounted in a few seconds, any soldering or crimping needless, dust-and waterproof up to IP69K



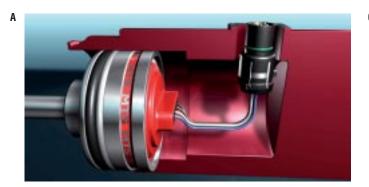
#### Technical Data

Input					
Measured variables:	Displacement				
Measuring range:	50 - 2500 mm in 5 mm steps				
Output	30 - 2300 mm in 3 mm steps				
Interface:					
	PWM				
Resolution:	The resolution is constant ± 0,1 mm				
Internal Cycle Time:	1 ms				
Cycle time:	adjustable 1 ms65 ms				
Accuracy	50.050				
Linearity:	50250 mm $\leq \pm 0,1$ mm 2552000 mm $\leq \pm 0,04$ % full stroke 20052500 mm $\leq \pm 0,8$ mm				
Hysteresis:	± 0,1 mm				
Setpoint Tolerance:	± 0,2 mm				
Operating conditions					
Assembly orientation:	In any direction				
Operating temperature electronics, storage temp.:	-40°C+105°C				
Fluid temperature:	-30°C+85°C				
Dew point, humidity:	90 % rel. humidity, no condensation acc. EN60068-2-30				
Pressure					
Operating pressure ratings:	<b>Ø 10 mm sensor rod</b> PN: 350 bar Pmax: 450 bar	<b>Ø 7 mm sensor rod</b> PN: 300 bar Pmax: 400 bar	Pressure pulse test acc. DIN EN ISO 19879		
IP rating					
M12 connector:	IP69K plugged, EN60529				
Sensor housing:	IP67, EN60529				
Environmental testing:					
Shock:	IEC-68-2-27				
	100 g (11 ms) single hit				
	50 g (11 ms) at 1000 Shocks per axis				
Vibration:					
	Ø 10 mm sensor rod 20g (r.m.s.)				
	Ø 7 mm sensor rod 15g (r.m.s.)				
EMC:	ISO 14982 agricultural and forestry machine	nes			
	ISO 14502 agricultura and lorestry machines				
	ISO 11452-4 (conducted immunity)				
	ISO 7637-1/2 (transient impulses)				
Materials and dimensions					
Sensor rod:	Stainless steel 1.4306 / AISI 304L (Ø 10 r	nm / Ø 7 mm)			
Housing:	Stainless steel 1.4305 /AISI 303				
Mechanical assembly:	Flange housing $\emptyset$ 48 mm				
Nicenanical assembly.	0-ring 40.87 x 3.53 mm NBR 80, backup	ring 12.6 x 18 x 1.4 PTEE			
Electrical installation					
Connector:	Connector System M12x1 with O-ring 7 x	1 35 mm NBB 70			
	Connecting flange brass nickel-plated with				
Supply voltage:	12/24 VDC (tolerance range 8 - 32 VDC)				
Voltage supply ripple:	< 1 % p-p				
Power drain:	< 1,5 W				
Electric strength:	500 VDC (DC ground to machine ground)				
Polarity protection (GND - VDC):	Up to -36 VDC				
Over voltage protection (GND - VDC):	Up to 36 VDC				

#### Temposonics® Connector System M12

**MTS presents the innovative Connector System for Temposonics**<sup>®</sup> **M-Series** The Temposonics<sup>®</sup> Connector System meets the most exacting protection requirements important for the difficult environmental conditions of mobile hydraulics applications. Protection type IP69K makes the robust metal housing not only completely dust- and waterproof, even the harshest cleaning measures can not damage the sensor.

- **A** The MH sensor is delivered by MTS together with the new Connector System: The connector insert carrier is already connected to the sensor conductors, i.e. no soldering, any colour or connection mistake.
- **B** The connector insert is taken out of the cylinder through a bore hole. The flange housing can be clicked in position easily from outside.
- **C** Four standard screws must be tightened to mount the Connector System on the cylinder.
- D With a corresponding mating plug the Connector System fulfills an IP rating of IP69K.





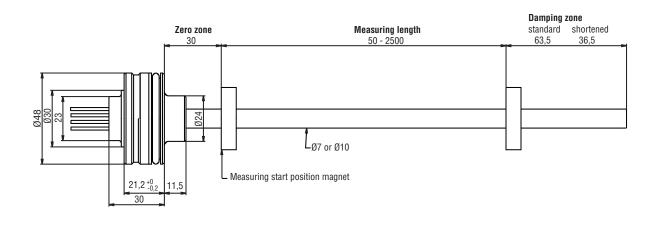


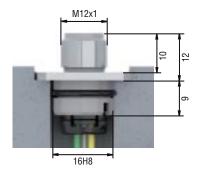


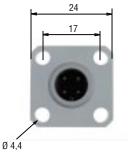
#### **Electrical Connection / Dimensions**

#### M12 connector system

4 single wire, 0,5 mm<sup>2</sup>









Pin	Signal
1	N.C.
2	Power Supply 12/24 VDC
3	DC Ground
4	PWM

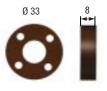


Ring magnet Part No. 401032 OD 17,4 mm ID 13,5 mm Height 8 mm Surface pressure max. 10 N/mm<sup>2\*</sup> in axial direction

\*max. mechanical burden, e.g. by circlip, lock washers etc.



Ring magnet Part No. 400533 OD 25,4 mm ID 13,5 mm Height 8 mm Surface pressure max. 40 N/mm<sup>2\*</sup> in axial direction

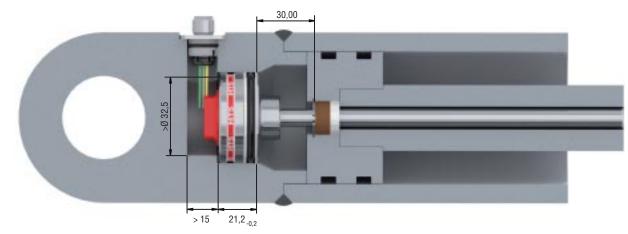


Ring magnet Part No. 201542-2 OD 33 mm ID 13,5 mm Height 8 mm Fixing holes 4,2 mm, circle Ø24 mm Surface pressure max. 40 N/mm<sup>2\*</sup> in axial direction Fastening torque for screws M4: max 1 Nm

#### **Mechanical Installation**

The robust Temposonics® model MH sensor's new stainless-steel housing is designed for direct stroke measurement in hydraulic cylinders. The Temposonics® MH sensor can be installed from the head side or the rod side of the cylinder depending on the cylinder design.

#### Example



#### **Sensor Installation**

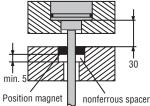
The method of installation is entirely dependent on the cylinder design. While the most common method of installation is from the rod side of the cylinder, installation from the head side of the cylinder is also possible. In both installation methods, the cylinder is sealed by O-ring and backup ring which is ready installed on the sensor housing.

#### Installation Notes

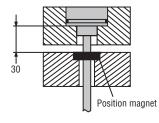
**Detail Flange Housing** 

- Use a non-ferrous circlip to fix the magnet.
- The bore in the piston rod is dependent on hydraulic pressure and piston velocity etc. The minimum drilling should be 10 (7 mm rod) or 13,5 mm (10 mm rod).

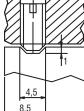
#### 1. Installation in magnetic Material with Spacer



#### 2. Installation in non-magnetic Material without Spacer

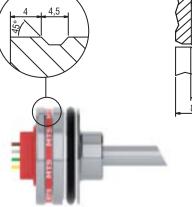


All dimensions in mm.



M5x10 (with flat point!) max. torque 0,5 Nm

e.g. retaining with set screw DIN 913



Temposonics M H M	3	
Sensor model MH = Hydraulic rod /		
Flange housing Ø 48 mm		
Form factor		
<b>C</b> = Rod-Ø 10 mm (damping zone 63,5 mm)		
D = Rod-Ø 7 mm (damping zone 63,5 mm) E = Rod-Ø 10 mm (reduced daming zone 36,5 mm)		
F = Rod-Ø 7 mm (reduced damping zone 36,5 mm)		
R = Rod-Ø 10 mm with rod end plug, threaded hole M4 (damping zone 63,5 mm)		
Measuring length		
0050 - 2500 mm in 5 mm steps		
Connection type		
Single wires with Connector System M12 N E = 4 single wires, 0,5 mm <sup>2</sup> with Connector System M12 IP69K, 4 pin		
NO6E = 60 mm min. wire length		
N25E = 250 mm max. wire length		
Input		
<b>3</b> = +12/24 VDC		
Output		
P = PWM		
15. digit: Span range $\mathbf{A} = 5 - 95 \% \cdot \mathbf{B} = 10 - 90 \% \cdot \mathbf{C} = 15 - 85 \% \cdot \mathbf{D} = 20 - 80 \% \cdot \mathbf{E} = 25 - 75$	%	

16. digit: Frequency  $\mathbf{A} = 50 \text{ Hz} \cdot \mathbf{B} = 60 \text{ Hz} \cdot \mathbf{C} = 100 \text{ Hz} \cdot \mathbf{D} = 200 \text{ Hz} \cdot \mathbf{E} = 300 \text{ Hz} \cdot \mathbf{F} = 400 \text{ Hz}$  $\mathbf{G} = 500 \text{ Hz} \cdot \mathbf{X} = \text{not defined}$ 

Scope of delivery Position sensor, O-Ring, backup-ring M12 connector system Please order magnets seperately!

Accessories (selection)	Part No.
<b>OD17,4 Ring magnet</b>	<b>401 032</b>
OD25,4 Ring magnet	400 533
OD33 Ring magnet	201 542-2

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